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LTI system Properties i terms of impulse response

Step Response

Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II)

Signals and Systems UNIT 3

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LTI system Properties in terms of impulse response

Please follow the below link for study material. • Link



Step Response

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LTI system Properties in terms of impulse response

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II) Characterizes the response to sudden changes in input. s[n] = h[n] * u[n] $= \sum_{k=-\infty}^{\infty} h[k]u[n-k]$ $u[n-k] \text{ exist from } -\infty \text{ to n}$ $s[n] = \sum_{k=-\infty}^{n} h[k]$

h[k] is the running sum of impulse response.

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Step Response for Continuous time system

$$s(t) = \int_{-\infty}^{t} h(\tau) d\tau$$

Relation b/w step response and impulse response.

$$h(t) = \frac{d}{dt}s(t)$$
$$h[n] = s[n] - s[n-1]$$

Eg. Step response of an RC ckt

$$h(t) = \frac{1}{RC} e^{-\frac{t}{RC}} u(t)$$



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Step Response Example

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Find the step response for LTI system represented by impulse response $h[n] = (\frac{1}{2})^n u[n]$.

Ans:

$$s[n] = \sum_{\substack{k=-\infty \\ n}}^{n} h[k]$$

$$s[n] = \sum_{k=0}^{n} (\frac{1}{2})^{k}$$

$$= \frac{1 - (\frac{1}{2})^{n+1}}{1 - \frac{1}{2}}, n \ge 0$$

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Diagram representations of LTI system (Direct Form-I and Direct Form -II)

Ans:

$$h(t) = tu(t)$$

$$s(t) = \int_{-\infty}^{t} h(\tau) d\tau$$
$$s(t) = \int_{0}^{t} \tau d\tau$$
$$= \frac{t^{2}}{2}, t \ge 0$$

Step Response Example

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II) Linear constant coefficient differential equation:

$$\sum_{k=0}^{N} a_k \frac{d^k}{dt^k} y(t) = \sum_{k=0}^{M} b_k \frac{d^k}{dt^k} x(t)$$

Linear constant coefficient difference equation:

$$\sum_{k=0}^{N} a_k y[n-k] = \sum_{k=0}^{M} b_k x[n-k]$$

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Order of the equation is (N,M), representing the number of energy storage devices in the system.

Often N>M and the order is described using only 'N'.

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Differential and Difference equation representation of LTI systems

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II) Second order difference equation:

 $y[n] + y[n - 1] + \frac{1}{4}y[n - 2] = x[n] + 2x[n - 1]$

Difference equation are easily arranged to obtain recursive formulas for computing the current o/p of the system.

$$\sum_{\substack{k=0\\M}}^{N} a_k y[n-k] = \sum_{\substack{k=0\\M}}^{M} b_k x[n-k]$$
$$y[n] = \frac{1}{a_0} \sum_{\substack{k=0\\M}}^{M} b_k x[n-k] - \frac{1}{a_0} \sum_{\substack{k=1\\M}}^{N} a_k y[n-k]$$
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 Shows how to obtain y[n] from present and past values of the input.

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Diagram representations of LTI system (Direct Form-I and Direct Form -II)

Find the first two o/p values y[0] and y[1] for the system described by $y[n] = x[n] + 2x[n - 1] - y[n - 1] - \frac{1}{4}y[n - 2]$. Assuming that the input is $x[n] = (\frac{1}{2})^n u[n]$ and the initial conditions are y[-1]=1 and y[-2]=-2. y[0] = x[0] + 2x[-1] - y[-1] - \frac{1}{4}y[-2] $y[1] = x[1] + 2x[0] - y[0] - \frac{1}{4}y[-1]$ $y[1] = \frac{1}{2} + 2x[-1] - \frac{1}{4}x(1) = 1\frac{3}{4}$

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II) Output of LTI system described by differential or difference equation has two components

- y^h -homogeneous solution
- y^p particular solution
- Complete solution

 $y = y^h + y^p$

Eg.

A system is described y the difference equation

y[n] - 1.143y[n-1] + 0.4128y[n-2] = 0.0675x[n] + 0.1349x[n-1] + 0.675x[n-2]

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y[-1] = 1 and y[-2] = 2,

Homogeneous Solution for CT system

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II) Set all terms involving input to zero $\sum_{k=0}^{N} a_k \frac{d^k}{dt^k} y(t) = \sum_{k=0}^{M} b_k \frac{d^k}{dt^k} x(t)$ $\sum_{k=0}^{N} a_k \frac{d^k}{dt^k} y(t) = 0$ $y^h(t) = \sum_{i=1}^{N} c_i e^{r_i t}$

riare the N roots of the characteristic equation

Homogeneous Solution for DT system

LTI system Properties in terms of impulse response

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II) $\sum_{k=0}^{N} a_k y[n-k] = \sum_{k=0}^{M} b_k x[n-k]$ Set all terms involving input to zero $\sum_{k=0}^{N} a_k y[n-k] = 0$ Solution $y^h[n] = \sum_{k=0}^{N} c_i r_i^n$

 r_i are the N roots of the characteristic equation.

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II) RC ckt depicted in figure is described by the differential equation $y(t) + RC \frac{d}{dt}y(t) = x(t)$. Determine the homogenous solution.



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The homogenous equation is

$$y(t) + RC\frac{d}{dt}y(t) = 0$$

Solution

$$y^h(t) = \sum_{i=1}^N c_i e^{r_i t}$$

$$y^h(t) = c_1 e^{r_1 t}$$

Characteristic equation $(1 + RCr_1) = 0$ $r_1 = -\frac{1}{RC}$

Homogenous solution of the system is

$$y^h(t) = c_1 e^{-\frac{1}{RC}t}$$

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Homogeneous Solution Example

Differential and Difference equation representation of LTI systems

Determine the homogenous solution.

$$\frac{d^2}{dt^2}y(t) + 5\frac{d}{dt}y(t) + 6y(t) =$$

$$2x(t) + \frac{d}{dt}x(t)$$

Ans:

Homogenous equation

$$\frac{d^2}{dt^2}y(t) + 5\frac{d}{dt}y(t) + 6y(t) = 0 \quad (1)$$

Homogenous solution

$$y^h(t) = \sum_{i=1}^N c_i e^{r_i t}$$

 $y^{h}(t) = c_{1}e^{r_{1}t} + c_{2}e^{r_{2}t}$

To find r_1 and r_2 solve CE.

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Put
$$\frac{d^n}{dt^n}y(t) = r^n$$

(1) becomes
 $r^2 + 5r + 6 = 0$

$$r = -3, -2$$

$$y^{h}(t) = c_{1}e^{-3t} + c_{2}e^{-2t}$$

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Homogeneous Solution Example

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Diagram representations of LTI system (Direct Form-I and Direct Form -II)

$$y[n] - \frac{1}{4}y[n-1] - \frac{1}{8}y[n-2] = x[n-1]$$

Ans:

Set input to zero

$$y[n] - \frac{1}{4}y[n-1] - \frac{1}{8}y[n-2] = 0$$
 (1)

0

N=2

$$y^{h}[n] = c_{1}r_{1}^{n} + c_{2}r_{2}^{n}$$

1) Becomes
 $1 - \frac{1}{4}r^{-1} - \frac{1}{8}r^{-2} =$

$$\begin{aligned} r^2 - \frac{1}{4}r - \frac{1}{8} &= 0 \\ r &= \frac{1}{2}, -\frac{1}{4} \\ y^h[n] &= c_1(\frac{1}{2})^n + c_2(-\frac{1}{4})^n \end{aligned}$$

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The Particular Solution

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LTI system Properties in terms of impulse response

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II) Solution of difference or differential equation for a given input. Assumption : output is of same general form as the input.

CT System		DT System	
Input	Particular solution	Input	Particular solution
1	с	1	с
t	$c_1 t + c_2$	n	$c_1 n + c_2$
e^{-at}	ce^{-at}	α^n	$c\alpha^n$
$\cos(\omega t + \Phi)$	$c_1 \cos(\omega t) + c_2 \sin(\omega t)$	$\cos(\Omega n + \Phi)$	$c_1 \cos(\Omega n) + c_2 \sin(\Omega n)$

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LTI system Properties in terms of impulse response

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II)

Procedure for calculating complete solution

1. Find the form of the homogeneous solution y^h from the roots of the CE equation.

2. Find a particular solution y^p by assuming that it is of the same form as the input, yet is independent of all terms in the homogeneous solution.

3. Determine the coefficients in the homogeneous solution so that the complete solution $y = y^h + y^p$ satisfies the initial conditions.

The Complete Solution

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The Complete Solution Example

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LTI system Properties in terms of impulse response

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II) Find the solution for the first order recursive system described by the difference equation.

$$y[n] - \frac{1}{4}y[n-1] = x[n]$$

If the input $x[n] = (\frac{1}{2})^n u[n]$ and the initial condition is y[-1] = 8.

Ans:

N=1

Homogenous solution

$$y[n] - \frac{1}{4}y[n-1] = 0$$

 $y^{h}[n] = c_{1}r^{n}$ $r^{n} - \frac{1}{4}r^{n-1} = 0$ $r - \frac{1}{4} = 0$ $y^{h}[n] = c_{1}(\frac{1}{4})^{n}$

Particular solution

$$y^{p}(n) = c_{2}(\frac{1}{2})^{n}$$

$$c_{2}(\frac{1}{2})^{n} - \frac{1}{4}c_{2}(\frac{1}{2})^{n-1} = (\frac{1}{2})^{n}$$

$$c_{2} - \frac{1}{2}c_{2} = 1$$

$$c_{2} = 2$$

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The Complete Solution Example Conti...

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Diagram representations of LTI system (Direct Form-I and Direct Form -II) Find the solution for the first order recursive system described by the difference equation.

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If the input $x[n] = (\frac{1}{2})^n u[n]$ and the initial condition is y[-1] = 8.

Ans:

N=1

Homogenous solution

$$y[n] - \frac{1}{4}y[n-1] = 0$$

 $y^{h}[n] = c_{1}r^{n}$ $r^{n} - \frac{1}{4}r^{n-1} = 0$ $r - \frac{1}{4} = 0$ $y^{h}[n] = c_{1}(\frac{1}{4})^{n}$

Particular solution

$$y^{p}(n) = c_{2}(\frac{1}{2})^{n}$$

$$c_{2}(\frac{1}{2})^{n} - \frac{1}{4}c_{2}(\frac{1}{2})^{n-1} = (\frac{1}{2})^{n}$$

$$c_{2} - \frac{1}{2}c_{2} = 1$$

$$c_{2} = 2$$

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Diagram representations of LTI system (Direct Form-I and Direct Form -II)



Basic Structures

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II)

System I Implementation using Basic Structures

 $v(n) = b_0 x(n) + b_1 x(n-1) + b_2 x(n-2)$



System-I

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Diagram representations of LTI system (Direct Form-I and Direct Form -II)

System II Implementation using Basic Structures

$$y(n) = v(n) - a_1 y(n-1) - a_2 y(n-2)$$



System-II

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Combined System Implementation

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II)



$$y(n) = -a_1 y(n-1) - a_2 y(n-2) + b_0 x(n) + b_1 x(n-1) + b_2 x(n-2)$$

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Diagram representations of LTI system (Direct Form-I and Direct Form -II)



Direct Form II

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Direct Form II Realization

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Diagram representations of LTI system (Direct Form-I and Direct Form -II)



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Step Response

Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II) Implement the system represented by following difference euqation

$$y(n) = \frac{4}{3}x(n) - x(n-1) + \frac{2}{3}x(n-2) + \frac{2}{3}y(n-1) - \frac{1}{3}y(n-2)$$



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System 1 Implementation

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$v(n) = \frac{4}{3}x(n) - x(n-1) + \frac{2}{3}x(n-2)$



LTI system Properties ir

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II)

System 2 Implementation

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$y(n) = v(n) + \frac{2}{3}y(n-1) - \frac{1}{3}y(n-2)$



Properties in terms of impulse response

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Differential and Difference equation representation of LTI systems

Diagram representations of LTI system (Direct Form-I and Direct Form -II)

Direct Form 1 Realization

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Diagram representations of LTI system (Direct Form-I and Direct Form -II)



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Changing the location of z^{-1} structures

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Direct Form 1 Realization

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