

Control Systems UNIT 2

Ripal Patel

Assistant Professor,
Dr.Ambedkar Institute of Technology, Bangalore.

ripal.patel.ec@drait.edu.in

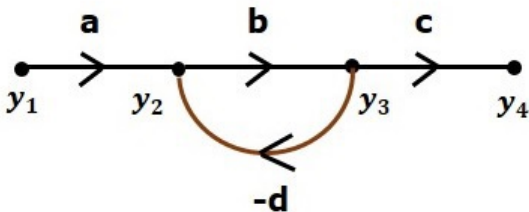
May 25, 2021

- Signal flow graph is a graphical representation of algebraic equations. In this chapter, let us discuss the basic concepts related signal flow graph and also learn how to draw signal flow graphs.

Nodes and branches are the basic elements of signal flow graph.

Node is a point which represents either a variable or a signal. There are three types of nodes input node, output node and mixed node.

- **Input Node** It is a node, which has only outgoing branches.
- **Output Node** It is a node, which has only incoming branches.
- **Mixed Node** It is a node, which has both incoming and outgoing branches.



The nodes present in this signal flow graph are y_1 , y_2 , y_3 and y_4 .

y_1 and y_4 are the input node and output node respectively.
 y_2 and y_3 are mixed nodes.

Branch is a line segment which joins two nodes. It has both gain and direction. For example, there are four branches in the above signal flow graph. These branches have gains of a , b , c and $-d$.

$$y_2 = a_{12}y_1 + a_{42}y_4$$

$$y_3 = a_{23}y_2 + a_{53}y_5$$

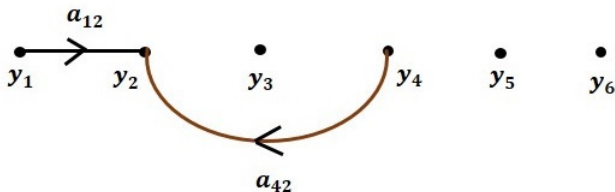
$$y_4 = a_{34}y_3$$

$$y_5 = a_{45}y_4 + a_{35}y_3$$

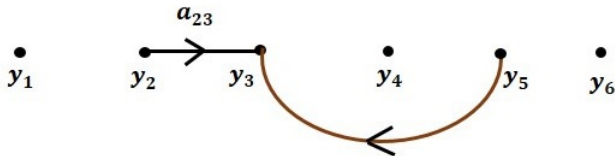
$$y_6 = a_{56}y_5$$

There will be six **nodes** (y_1 , y_2 , y_3 , y_4 , y_5 and y_6) and eight **branches** in this signal flow graph. The gains of the branches are a_{12} , a_{23} , a_{34} , a_{45} , a_{56} , a_{42} , a_{53} and a_{35} .

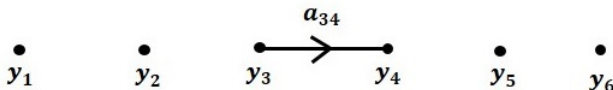
Step 1 – Signal flow graph for $y_2 = a_{13}y_1 + a_{42}y_4$ is shown in the following figure.



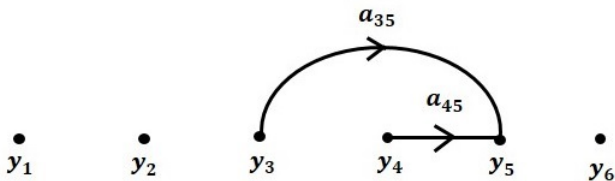
Step 2 – Signal flow graph for $y_3 = a_{23}y_2 + a_{53}y_5$ is shown in the following figure.



Step 3 – Signal flow graph for $y_4 = a_{34}y_3$ is shown in the following figure.



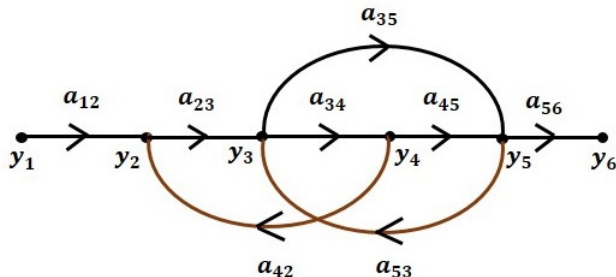
Step 4 – Signal flow graph for $y_5 = a_{45}y_4 + a_{35}y_3$ is shown in the following figure.



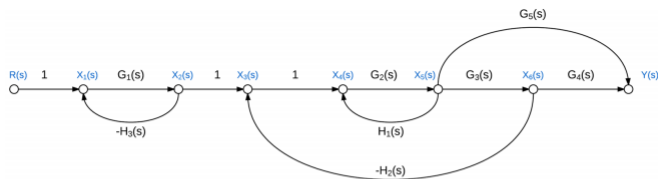
Step 5 – Signal flow graph for $y_6 = a_{56}y_5$ is shown in the following figure.



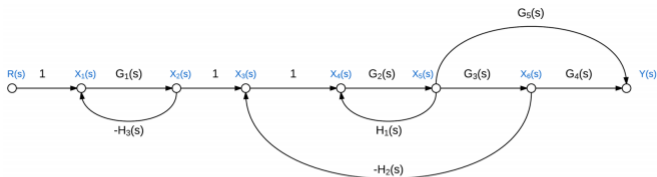
Step 6 – Signal flow graph of overall system is shown in the following figure.



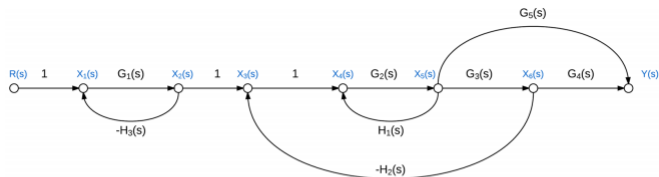
- Suppose there are N forward paths in a signal flow graph. The gain between the input and the output nodes of a signal flow graph is nothing but the transfer function of the system. It can be calculated by using Mason's gain formula.
- We've seen how to reduce a complicated block diagram to a single input-output transfer function.
- Mason's rule provides a formula to calculate the same overall transfer function.
- Before presenting the Mason's rule formula, we need to define some terminology.



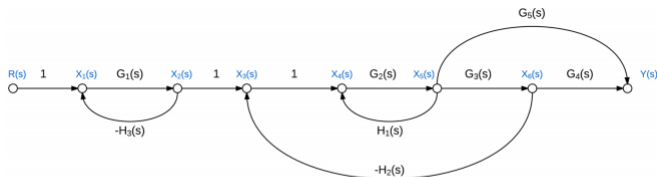
- **Loop gain** – total gain (product of individual gains) around any path in the signal flow graph
 - ▣ Beginning and ending at the same node
 - ▣ Not passing through any node more than once
- Here, there are three loops with the following gains:
 1. $-G_1H_3$
 2. G_2H_1
 3. $-G_2G_3H_2$



- **Forward path gain** – gain along any path from the input to the output
 - ▣ Not passing through any node more than once
- Here, there are two forward paths with the following gains:
 1. $G_1 G_2 G_3 G_4$
 2. $G_1 G_2 G_5$



- **Non-touching loops** – loops that do not have any nodes in common
- Here,
 1. $-G_1H_3$ does not touch G_2H_1
 2. $-G_1H_3$ does not touch $-G_2G_3H_2$



- **Non-touching loop gains** – the *product* of loop gains from non-touching loops, taken two, three, four, or more at a time
- Here, there are only two *pairs* of non-touching loops
 1. $[-G_1 H_3] \cdot [G_2 H_1]$
 2. $[-G_1 H_3] \cdot [-G_2 G_3 H_2]$

Masons gain formula is

$$T = \frac{C(s)}{R(s)} = \frac{\sum_{i=1}^N P_i \Delta_i}{\Delta}$$

Where,

- **C(s)** is the output node
- **R(s)** is the input node
- **T** is the transfer function or gain between $R(s)$ and $C(s)$
- **P_i** is the i^{th} forward path gain

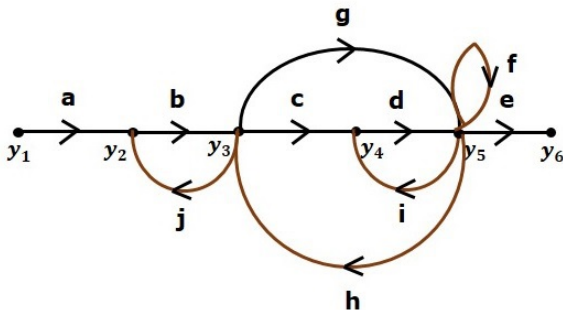
$$\Delta = 1 - (\text{sum of all individual loop gains})$$

+ (sum of gain products of all possible two nontouching loops)

− (sum of gain products of all possible three nontouching loops) + ...

Δ_i is obtained from Δ by removing the loops which are touching the i^{th} forward path.

Consider the following signal flow graph in order to understand the basic terminology involved here.



Path

It is a traversal of branches from one node to any other node in the direction of branch arrows. It should not traverse any node more than once.

Examples - $y_2 \rightarrow y_3 \rightarrow y_4 \rightarrow y_5$ and $y_5 \rightarrow y_3 \rightarrow y_2$

Forward Path

The path that exists from the input node to the output node is known as **forward path**.

Examples - $y_1 \rightarrow y_2 \rightarrow y_3 \rightarrow y_4 \rightarrow y_5 \rightarrow y_6$ and $y_1 \rightarrow y_2 \rightarrow y_3 \rightarrow y_5 \rightarrow y_6$.

Forward Path Gain

It is obtained by calculating the product of all branch gains of the forward path.

Examples - $abcde$ is the forward path gain of $y_1 \rightarrow y_2 \rightarrow y_3 \rightarrow y_4 \rightarrow y_5 \rightarrow y_6$

and $abge$ is the forward path gain of $y_1 \rightarrow y_2 \rightarrow y_3 \rightarrow y_5 \rightarrow y_6$.

Loop

The path that starts from one node and ends at the same node is known as **loop**. Hence, it is a closed path.

Examples - $y_2 \rightarrow y_3 \rightarrow y_2$ and $y_3 \rightarrow y_5 \rightarrow y_3$.

Loop Gain

It is obtained by calculating the product of all branch gains of a loop.

Examples - b_j is the loop gain of $y_2 \rightarrow y_3 \rightarrow y_2$ and g_h is the loop gain of

$y_3 \rightarrow y_5 \rightarrow y_3$.

Non-touching Loops

These are the loops, which should not have any common node.

Examples - The loops, $y_2 \rightarrow y_3 \rightarrow y_2$ and $y_4 \rightarrow y_5 \rightarrow y_4$ are non-touching.

Calculation of Transfer Function using Mason's Gain Formula

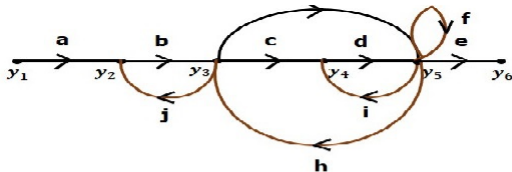
Signal Flow
Graphs

Signal Flow
Graph
Terminology

Mason's Gain
Formula

Examples

Construction
of Signal flow
graph for closed loop
control
systems



- ▣ Number of forward paths, $N = 2$.
- ▣ First forward path is - $y_1 \rightarrow y_2 \rightarrow y_3 \rightarrow y_4 \rightarrow y_5 \rightarrow y_6$.
- ▣ First forward path gain, $p_1 = abcde$.
- ▣ Second forward path is - $y_1 \rightarrow y_2 \rightarrow y_3 \rightarrow y_5 \rightarrow y_6$.
- ▣ Second forward path gain, $p_2 = abge$.
- ▣ Number of individual loops, $L = 5$.

Calculation of Transfer Function using Masons Gain Formula

Signal Flow
Graphs

Signal Flow
Graph
Terminology

Mason's Gain
Formula

Examples

Construction
of Signal flow
graph for
closed loop
control
systems

- Loops are - $y_2 \rightarrow y_3 \rightarrow y_2$, $y_3 \rightarrow y_5 \rightarrow y_3$, $y_3 \rightarrow y_4 \rightarrow y_5 \rightarrow y_3$,
 $y_4 \rightarrow y_5 \rightarrow y_4$ and $y_5 \rightarrow y_5$.
- Loop gains are - $l_1 = bj$, $l_2 = gh$, $l_3 = cdh$, $l_4 = di$ and $l_5 = f$.
- Number of two non-touching loops = 2.
- First non-touching loops pair is - $y_2 \rightarrow y_3 \rightarrow y_2$, $y_4 \rightarrow y_5 \rightarrow y_4$.
- Gain product of first non-touching loops pair, $l_1 l_4 = bjdi$
- Second non-touching loops pair is - $y_2 \rightarrow y_3 \rightarrow y_2$, $y_5 \rightarrow y_5$.
- Gain product of second non-touching loops pair is - $l_1 l_5 = bjf$

Calculation of Transfer Function using Mason's Gain Formula

Signal Flow
Graphs

Signal Flow
Graph
Terminology

Mason's Gain
Formula

Examples

Construction
of Signal flow
graph for
closed loop
control
systems

Higher number of (more than two) non-touching loops are not present in this signal flow graph.

We know,

$$\Delta = 1 - (\text{sum of all individual loop gains})$$

$$+ (\text{sum of gain products of all possible two nontouching loops})$$

$$- (\text{sum of gain products of all possible three nontouching loops}) + \dots$$

Substitute the values in the above equation,

$$\Delta = 1 - (bj + gh + cdh + di + f) + (bjdi + bjf) - (0)$$

$$\Rightarrow \Delta = 1 - (bj + gh + cdh + di + f) + bjdi + bjf$$

There is no loop which is non-touching to the first forward path.

So, $\Delta_1 = 1$.

Similarly, $\Delta_2 = 1$. Since, no loop which is non-touching to the second forward path.

Calculation of Transfer Function using Mason's Gain Formula

Signal Flow
Graphs

Signal Flow
Graph
Terminology

Mason's Gain
Formula

Examples

Construction
of Signal flow
graph for
closed loop
control
systems

Substitute, $N = 2$ in Mason's gain formula

$$T = \frac{C(s)}{R(s)} = \frac{\sum_{i=1}^2 P_i \Delta_i}{\Delta}$$

$$T = \frac{C(s)}{R(s)} = \frac{P_1 \Delta_1 + P_2 \Delta_2}{\Delta}$$

Substitute all the necessary values in the above equation.

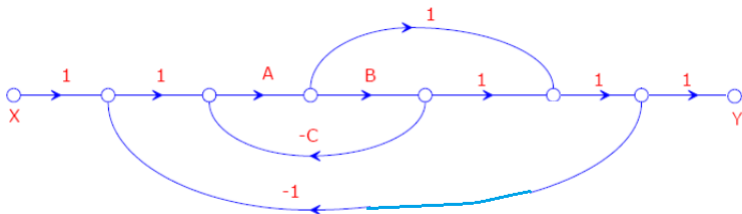
$$T = \frac{C(s)}{R(s)} = \frac{(abcde)1 + (abge)1}{1 - (bj + gh + cdh + di + f) + bjdi + bjf}$$

$$\Rightarrow T = \frac{C(s)}{R(s)} = \frac{(abcde) + (abge)}{1 - (bj + gh + cdh + di + f) + bjdi + bjf}$$

Therefore, the transfer function is -

$$T = \frac{C(s)}{R(s)} = \frac{(abcde) + (abge)}{1 - (bj + gh + cdh + di + f) + bjdi + bjf}$$

Using Mason's Formula, Find the T.F. $Y(s)/X(s)$



$$P_1 = AB ; P_2 = A$$

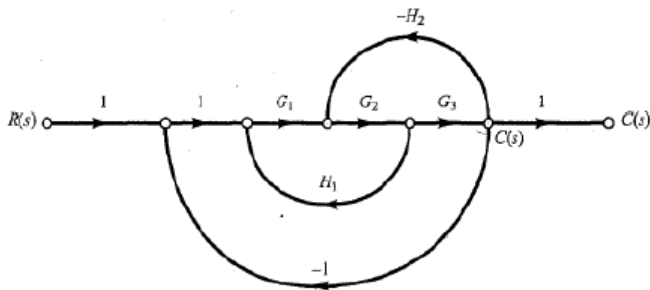
$$\Delta = 1 - (-ABC - AB - A)$$

$$\Delta = 1 + ABC + AB + A$$

$$\Delta_1 = 1 ; \Delta_2 = 1$$

$$\frac{Y}{X} = \frac{P_1\Delta_1 + P_2\Delta_2}{\Delta} = \frac{A(1+B)}{1+ABC+AB+A}$$

Using Mason's Formula, Find the T.F. $C(s)/R(s)$



In this system there is only one forward path between the input $R(s)$ and the output $C(s)$. The forward path gain is

$$P_1 = G_1 G_2 G_3$$

we see that there are three individual loops. The gains of these loops are

$$L_1 = G_1 G_2 H_1$$

$$L_2 = -G_2 G_3 H_2$$

$$L_3 = -G_1 G_2 G_3$$

Note that since all three loops have a common branch, there are no non-touching loops. Hence, the determinant Δ is given by

$$\begin{aligned}\Delta &= 1 - (L_1 + L_2 + L_3) \\ &= 1 - G_1G_2H_1 + G_2G_3H_2 + G_1G_2G_3\end{aligned}$$

The cofactor Δ_1 of the determinant along the forward path connecting the input node and output node is obtained from Δ by removing the loops that touch this path. Since path P_1 touches all three loops, we obtain

$$\Delta_1 = 1$$

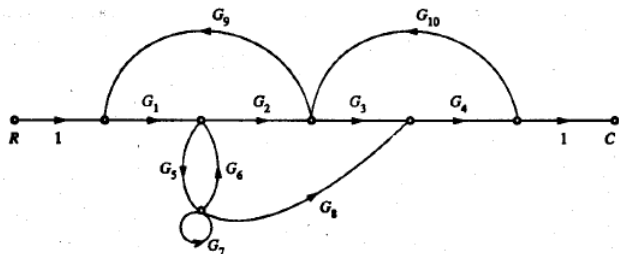
Therefore, the overall gain between the input $R(s)$ and the output $C(s)$, or the closed-loop transfer function, is given by

$$\frac{C(s)}{R(s)} = \frac{G_1G_2G_3}{1 - G_1G_2H_1 + G_2G_3H_2 + G_1G_2G_3}$$

Ripal Patel

Signal Flow
GraphsSignal Flow
Graph
TerminologyMason's Gain
Formula

Examples

Construction
of Signal flow
graph for
closed loop
control
systemsUsing Mason's Formula, Find the T.F. $C(s)/R(s)$ 

Two forward Path

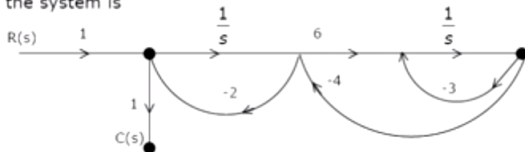
Four Loops

Two non-touching loops: Three

$$\frac{C}{R} = \frac{P_1 \Delta_1 + P_2 \Delta_2}{\Delta}$$

$$= \frac{G_1 G_2 G_3 G_4 (1 - G_7) + G_1 G_5 G_8 G_4}{1 - [G_1 G_2 G_9 + G_3 G_4 G_{10} + G_1 G_5 G_8 G_4 G_{10} G_9 + G_5 G_6 + G_7] + [G_1 G_2 G_9 G_7 + G_3 G_4 G_{10} G_5 G_6 + G_3 G_4 G_{10} G_7]}$$

The signal flow graph of a system is shown in figure. The transfer function $\frac{C(s)}{R(s)}$ of the system is



(a) $\frac{6}{s^2 + 29s + 6}$

(b) $\frac{6s}{s^2 + 29s + 6}$

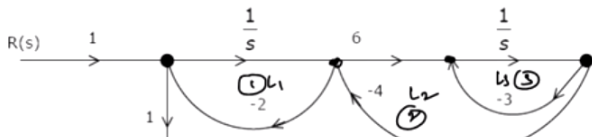
(c) $\frac{s(s+2)}{s^2 + 29s + 6}$

(d) $\frac{s(s+27)}{s^2 + 29s + 6}$

Ripal Patel

Signal Flow
GraphsSignal Flow
Graph
TerminologyMason's Gain
Formula

Examples

Construction
of Signal flow
graph for
closed loop
control
systems

$$L_1 = -2/s, L_2 = -24/s$$

$$L_3 = -3/s$$

L_1 & L_3 - non touching loops

$$L_1 L_3 = 6/s^2$$

$$\Delta = 1 - (-2/s - 24/s - 3/s)$$

$$+ (6/s^2)$$

$$\Delta = 1 + 29/s + 6/s^2 \quad \text{--- (1)}$$

Ripal Patel

Signal Flow
GraphsSignal Flow
Graph
TerminologyMason's Gain
Formula

Examples

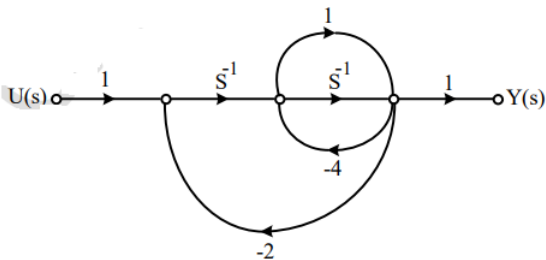
Construction
of Signal flow
graph for
closed loop
control
systems

$$P_i = i^{\text{th}} \text{ forward path gain} = 1 \cdot 1 = 1$$

$$\Delta_i = 1 - (L_2 + L_3) = 1 + \frac{24}{s} + \frac{3}{s} = 1 + \frac{27}{s}$$

$$\frac{C(s)}{R(s)} = \frac{P_i \Delta_i}{\Delta} = \frac{(1 + \frac{27}{s})}{(1 + \frac{29}{s} + \frac{6}{s^2})} = \frac{(s + 27)(\frac{1}{s})}{(s^2 + 29s + 6)(\frac{1}{s^2})}$$

The signal flow graph for a system is given below. The transfer function $Y(s)/U(s)$



(a) $\frac{s+1}{5s^2+6s+2}$

(b) $\frac{s+1}{s^2+6s+2}$

(c) $\frac{s+1}{s^2+4s+2}$

(d) $\frac{1}{5s^2+6s+2}$

Soln. The forward path transmittance $P_1 = S^{-1} \times S^1 = \frac{1}{S^2}$

The forward path transmittance $P_2 = S^{-1} = \frac{1}{S}$

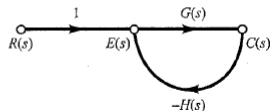
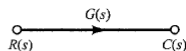
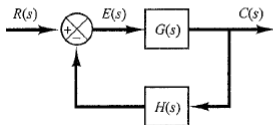
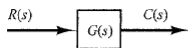
$$\Delta_1 = 1, \Delta_2 = 1$$

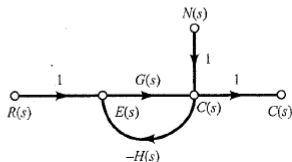
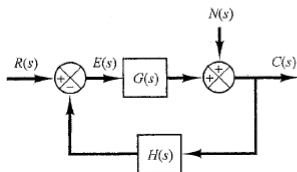
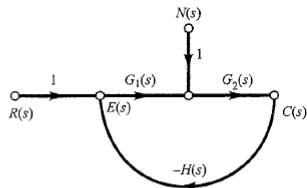
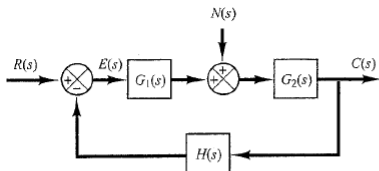
$$\Delta = 1 - (-2S^{-2} - 2S^{-1} - 4S^{-1} - 4)$$

$$= 1 + \frac{2}{S^2} + \frac{2}{S} + \frac{4}{S} + 4$$

$$= 1 + \frac{2}{S^2} + \frac{2}{S} + \frac{4}{S} + 4$$

$$= (5S^2 + 6S + 2)/S^2$$

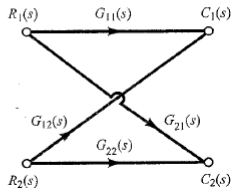
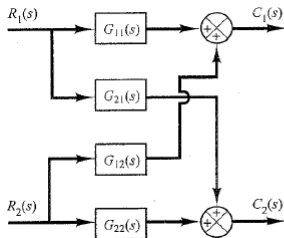




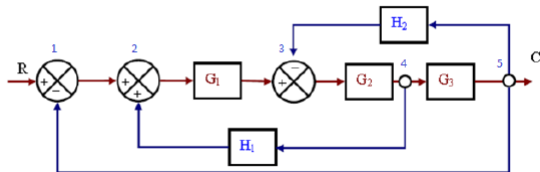
Ripal Patel

Signal Flow
GraphsSignal Flow
Graph
TerminologyMason's Gain
Formula

Examples

Construction
of Signal flow
graph for
closed loop
control
systems

Draw the DFG from the block diagram given below.



Solution of Example: Signal flow graph from Block Diagram

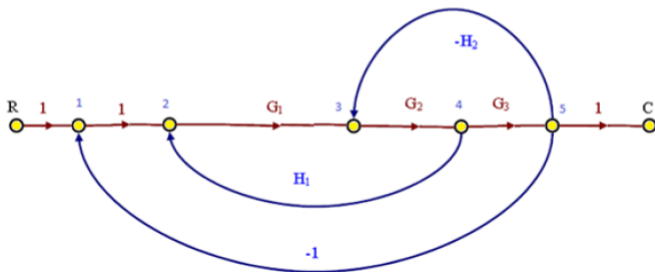
Ripal Patel

Signal Flow
GraphsSignal Flow
Graph
TerminologyMason's Gain
Formula

Examples

Construction
of Signal flow
graph for
closed loop
control systems

Choose the nodes to represent the variables say 1, 2, .. 5 as shown in the block diagram above. Connect the nodes with appropriate gain along the branch. The signal flow graph is shown below.



The End